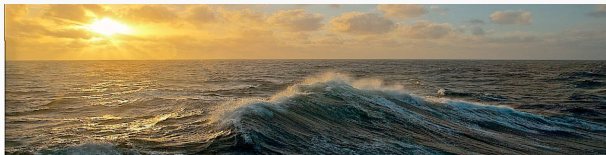


Absorbing Boundary Condition, Domain Decomposition and Hydrodynamic Wave Model

O. Wilk

M2N/IMath/Cnam

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le **cnam**

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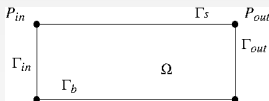
Num. appli. (hydro. wave model)

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The hydrodynamic wave model (Ph. D. ¹) (without flow):

$$\left\{ \begin{array}{l} \partial_t^2 \eta - c_r^2 \partial_x^2 \eta + \frac{g}{2\varepsilon} \eta + \frac{1}{2\varepsilon} \dot{\varphi} = 0 \text{ on } \Gamma_s, \quad c_r = \sqrt{\sigma / (2\varepsilon\rho)}, \\ \partial_t^2 \varphi - c_f^2 \Delta \varphi = 0 \text{ in } \Omega, \\ \frac{\partial \varphi}{\partial \nu} = \partial_t \eta \text{ on } \Gamma_s, \\ + \text{I.C.} \end{array} \right.$$



Tests with the Engquist-Majda boundary condition of order one ², interesting results for initial conditions in the domain not on the surface.

So we want to test a high-order boundary condition (Higdon ... Hagstrom - Warburton).

¹ ... Neumann-Kelvin ... - Ana. App., Vol. 8, No. 4 (2010) 1–26

² mémoire Cnam - D.M. Bissengue, PH. Destuynder, O. Wilk

A history ... (1/3)

- Wave eq. (Engquist-Majda (1977), Higdon (86)),
- dispersive wave eq. (Hagstrom (99), Hagstrom, Mass-or, Givoli (2008)),
- with flow (Bécache, Givoli, Hagstrom (2010)).

High-order boundary condition of order $p + 1$:

$$(a_p \partial_t + c \partial_\nu) \dots (a_1 \partial_t + c \partial_\nu) (a_0 \partial_t + c \partial_\nu) u = 0, a_i \leq 1, i = 0, p.$$

Not easy to use.

A history ... (2/3)

Auxiliary variable formulations :

- Givoli, Neta (2003) (unstable for $t \nearrow$) :

$$(a_0 \partial_t + c \partial_\nu) u = \phi_1,$$

$$(a_1 \partial_t + c \partial_\nu) \phi_1 = \phi_2,$$

\vdots

$$\phi_{p+1} = 0.$$

- Hagstrom, Warburton (2004) (more stable) :

$$(a_0 \partial_t + c \partial_\nu) u = a_0 \partial_t \phi_1,$$

$$(a_1 \partial_t + c \partial_\nu) \phi_1 = (a_1 \partial_t - c \partial_\nu) \phi_2,$$

\vdots

$$\phi_{p+1} = 0.$$

Equivalent to :

$$(a_0 \partial_t + c \partial_\nu) \left[\prod_{j=1}^p (a_j \partial_t + c \partial_\nu)^2 \right] u = 0$$

A history ... (3/3)

An example with the dispersive problem :

$$\partial_t^2 u - c^2 \partial_x^2 u - c^2 \partial_y^2 u + f^2 u = 0 \text{ in } \mathbb{R} + C.I.$$

Linearity (boundary cond.) + I.C. equal to zero ($a_j = 1$), we get :

$$\partial_t^2 \phi_j - c^2 \partial_x^2 \phi_j - c^2 \partial_y^2 \phi_j + f^2 \phi_j = 0, \forall j = 1, p.$$

Replace " $c^2 \partial_x^2 \phi_j$ " (ex. with the Givoli-Neta formulation) :

$$\begin{aligned} c^2 \partial_x^2 \phi_j &= (c \partial_x - \partial_t) (c \partial_x + \partial_t) \phi_j + \partial_t^2 \phi_j \\ c^2 \partial_x^2 \phi_j &= (c \partial_x - \partial_t) \phi_{j+1} + \partial_t^2 \phi_j \\ \text{et } (c \partial_x + \partial_t) \phi_{j+1} &= \phi_{j+2} \end{aligned}$$

we get just on the boundary ($\forall j = 1, p, \phi_0 = u$) :

$$\partial_t^2 \phi_{j-1} + 2 \partial_t \phi_j - \phi_{j+1} - c^2 \partial_y^2 \phi_{j-1} + f^2 \phi_{j-1} = 0.$$

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A coupled model.

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H.W. A.B.C. with the surface model

$$\partial_t^2 \eta - c_r^2 \partial_x^2 \eta + \frac{g}{2\varepsilon} \eta + \frac{1}{2\varepsilon} \dot{\varphi} = 0 \text{ on } \Gamma_s \iff \mathcal{L}_1(\eta) + \mathcal{L}_2(\varphi) = 0 \text{ on } \Gamma_s,$$

$$(\mathbf{a}_{r0} \partial_t + \mathbf{c}_r \partial_\nu) \eta = \mathbf{a}_{r0} \partial_t \phi_1^\eta, \quad (\mathbf{a}_{f0} \partial_t + \mathbf{c}_f \partial_\nu) \varphi = \mathbf{a}_{f0} \partial_t \phi_1^\varphi,$$

$$\mathcal{L}_1((\mathbf{a}_{r0} \partial_t + \mathbf{c}_r \partial_\nu) \eta) = \mathcal{L}_1(\mathbf{a}_{r0} \partial_t \phi_1^\eta), \quad \mathcal{L}_2((\mathbf{a}_{f0} \partial_t + \mathbf{c}_f \partial_\nu) \varphi) = \mathcal{L}_2(\mathbf{a}_{f0} \partial_t \phi_1^\varphi),$$

$$(\mathbf{a}_{r0} \partial_t + \mathbf{c}_r \partial_\nu) \mathcal{L}_1(\eta) = \mathbf{a}_{r0} \partial_t \mathcal{L}_1(\phi_1^\eta), \quad (\mathbf{a}_{f0} \partial_t + \mathbf{c}_f \partial_\nu) \mathcal{L}_2(\varphi) = \mathbf{a}_{f0} \partial_t \mathcal{L}_2(\phi_1^\varphi),$$

$$(\partial_t + \mathbf{C}_r \partial_\nu) \mathcal{L}_1(\eta) = \partial_t \mathcal{L}_1(\phi_1^\eta), \quad (\partial_t + \mathbf{C}_f \partial_\nu) \mathcal{L}_2(\varphi) = \partial_t \mathcal{L}_2(\phi_1^\varphi).$$

If $\mathbf{C}_r = \mathbf{C}_f = \mathbf{C}$, we get :

$$(\partial_t + \mathbf{C} \partial_\nu)(\mathcal{L}_1(\eta) + \mathcal{L}_2(\varphi)) = \partial_t(\mathcal{L}_1(\phi_1^\eta) + \mathcal{L}_2(\phi_1^\varphi)),$$

so :

$$\partial_t(\mathcal{L}_1(\phi_1^\eta) + \mathcal{L}_2(\phi_1^\varphi)) = 0 \text{ on } \Gamma_s,$$

with I.C. equal to zero, we get :

$$\mathcal{L}_1(\phi_1^\eta) + \mathcal{L}_2(\phi_1^\varphi) = 0 \text{ on } \Gamma_s.$$

And also, we get $\forall \phi_i, i = 1, p$:

$$\mathcal{L}_1(\phi_i^\eta) + \mathcal{L}_2(\phi_i^\varphi) = 0 \text{ on } \Gamma_s.$$

H.W. A.B.C. with the basin model

In the domain, we get (without condition on the coefficients) :

$$\partial_t^2 \phi_i^\varphi - c_f^2 \Delta \phi_i^\varphi = 0 \text{ in } \Omega, \forall i = 1, p.$$

But for the condition between the surface model and the domain model :

$$\partial_\nu \varphi = \partial_t \eta \text{ on } \Gamma_s,$$

we get (if $C_r = C_f = C$) :

$$\partial_\nu \phi_i^\varphi = \partial_t \phi_i^\eta \text{ on } \Gamma_s, \forall i = 1, p.$$

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$$\left. \begin{array}{l} (a_0 \partial_t + c_r \partial_x) \eta = a_0 \partial_t \phi_1^\eta \text{ at } P_{out}, \\ (a_0 \partial_t + c_r \partial_x) \varphi = a_0 \partial_t \phi_1^\varphi \text{ on } \Gamma_{out}, \end{array} \right\}$$

$$\forall j = 1, \dots, J \text{ at } P_{out} :$$

$$\left. \begin{array}{l} l_{j,j-1} \partial_t^2 \phi_{j-1}^\eta + l_{j,j} \partial_t^2 \phi_j^\eta + l_{j,j+1} \partial_t^2 \phi_{j+1}^\eta \\ + \frac{g}{2\varepsilon} (m_{j,j-1} \phi_{j-1}^\eta + m_{j,j} \phi_j^\eta + m_{j,j+1} \phi_{j+1}^\eta) \\ + \frac{1}{2\varepsilon} (m_{j,j-1} \partial_t \phi_{j-1}^\varphi + m_{j,j} \partial_t \phi_j^\varphi + m_{j,j+1} \partial_t \phi_{j+1}^\varphi) = 0, \end{array} \right\}$$

$$\forall j = 1, \dots, J \text{ on } \Gamma_{out} :$$

$$\left. \begin{array}{l} l_{j,j-1} \partial_t^2 \phi_{j-1}^\varphi + l_{j,j} \partial_t^2 \phi_j^\varphi + l_{j,j+1} \partial_t^2 \phi_{j+1}^\varphi \\ - c_f^2 (m_{j,j-1} \partial_y^2 \phi_{j-1}^\varphi + m_{j,j} \partial_y^2 \phi_j^\varphi + m_{j,j+1} \partial_y^2 \phi_{j+1}^\varphi) = 0, \end{array} \right\}$$

$$\left\{ \begin{array}{l} \frac{\partial \phi_j^\varphi}{\partial \nu} = \partial_t \phi_j^\eta \text{ at } P_{out}, \frac{\partial \phi_j^\varphi}{\partial \nu} = 0 \text{ at the other end.} \end{array} \right.$$

Wave speed on the surface : useful for a (1/2)

Top $y = 0$, bottom $y = h, h < 0$ ¹:

$$\begin{cases} (i) : & 2\varepsilon\partial_t^2\eta - \frac{\sigma}{\rho}\partial_x^2\eta + g\eta + \dot{\varphi} = 0 \text{ on } \Gamma_s, (\varepsilon \text{ small}) \\ (ii) : & \partial_t^2\varphi - c_f^2\Delta\varphi = 0 \text{ in } \Omega, \text{ with } \frac{\partial\varphi}{\partial\nu} = \partial_t\eta \text{ on } \Gamma_s \end{cases}$$

$$\partial_t(i) \text{ et } \partial_t\eta = \partial_\nu\varphi : -\frac{\sigma}{\rho}\partial_x^2\partial_y\varphi + g\partial_y\varphi + \ddot{\varphi} = 0 \text{ on } \Gamma_s,$$

with $\varphi = A(y) \exp^{i(kx - \omega t)}$ (remark : $C = \omega/k$) :

$$\begin{cases} (iii) : & (g + \frac{\sigma}{\rho}k^2)\dot{A}(y) - \omega^2 A(y) = 0 \text{ on } \Gamma_s(y = 0), \\ (iv) : & \ddot{A}(y) - l^2 A(y) = 0 \text{ dans } \Omega, \text{ with } l = \sqrt{\frac{c_f^2 k^2 - \omega^2}{c_f^2}} \end{cases}$$

hyp. : $c_f k > \omega$

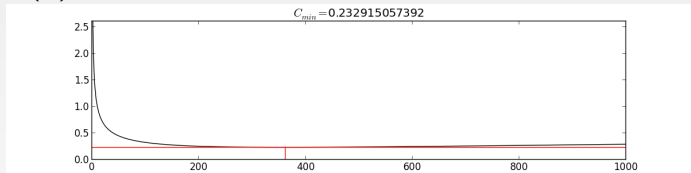
$$(iv) \Rightarrow A(y) = K_1 \exp(ly) + K_2 \exp(-ly),$$
$$= K_1 \exp(ly) \text{ small } \partial_\nu|_{y=h} = 0, h \rightarrow -\infty \text{ and } |y| \text{ small.}$$

$$(iii) \text{ if } l \simeq k \Rightarrow C = \frac{\omega}{k} = \pm \sqrt{\frac{g}{k} + \frac{\sigma}{\rho}k} \text{ with } C_{min} = \left(\frac{4\sigma g}{\rho}\right)^{1/4}.$$

¹J. Fabre

Wave speed on the surface : useful for a (2/2)

$C(k)$ ($\sigma = 0.075 N.m^{-1}$, $\rho = 1000 kg.m^{-3}$, $g = 9.81 m.s^{-2}$) :

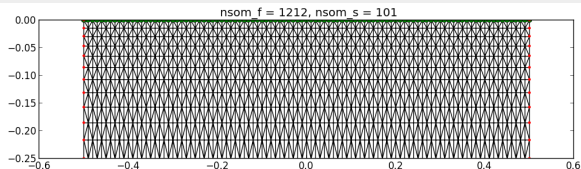


$$\text{If } l = k \sqrt{1 - \frac{\omega^2}{c_f^2 k^2}} \Rightarrow \tilde{C} = C \underbrace{\left(1 - \frac{\omega^2}{c_f^2 k^2}\right)^{1/4}}_{< 1}.$$

So to absorb the waves with a speed $< C_{min}$:

$$a_f > c_f / C_{min}, \quad a_r = (c_r / c_f) a_f.$$

Numerical application : (1/2)



$$c_f = 1000 \text{ m.s}^{-1}, J = 4, a = 1.3 c_f / C_{min} - 1.5 c_f / C_{min}.$$

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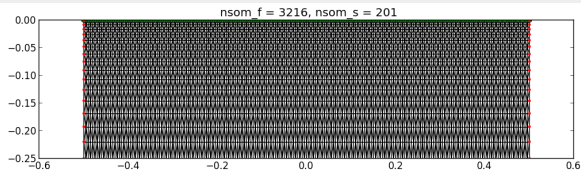
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Numerical application : (2/2)



$$c_f = 1000 m \cdot s^{-1}, J = 4, a = 1.8 c_f / C_{min} - 2.0 c_f / C_{min}.$$

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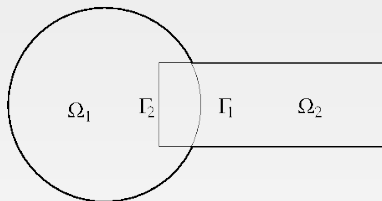
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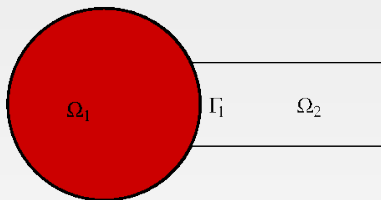


- P.L. Lions (1988) (parallel)

$$\begin{aligned} \Delta u_1^n &= 0 & \text{in } \Omega_1 & & \Delta u_2^n &= 0 & \text{in } \Omega_2 \\ u_1^n &= g & \text{on } \partial\Omega \cap \bar{\Omega}_1 & & u_2^n &= g & \text{on } \partial\Omega \cap \bar{\Omega}_2 \\ u_1^n &= u_2^{n-1} & \text{on } \Gamma_1 & & u_2^n &= u_1^{n-1} & \text{on } \Gamma_2 \end{aligned}$$

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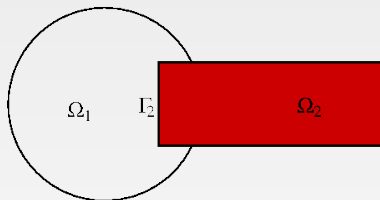
$$\begin{aligned}\Delta u_1^1 &= 0 && \text{in } \Omega_1 \\ u_1^1 &= g && \text{on } \partial\Omega \cap \bar{\Omega}_1 \\ u_1^1 &= u_2^0 && \text{on } \Gamma_1\end{aligned}$$

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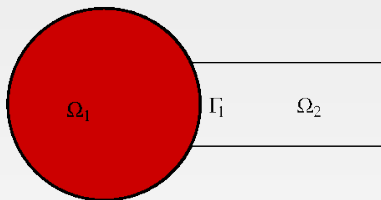
$$\begin{aligned}\Delta u_2^1 &= 0 && \text{in } \Omega_2 \\ u_2^1 &= g && \text{on } \partial\Omega \cap \bar{\Omega}_2 \\ u_2^1 &= u_1^1 && \text{on } \Gamma_2\end{aligned}$$

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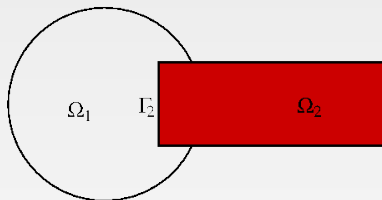
$$\begin{aligned}\Delta u_1^2 &= 0 && \text{in } \Omega_1 \\ u_1^2 &= g && \text{on } \partial\Omega \cap \bar{\Omega}_1 \\ u_1^2 &= u_2^1 && \text{on } \Gamma_1\end{aligned}$$

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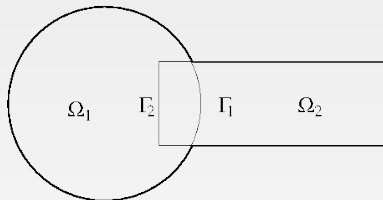
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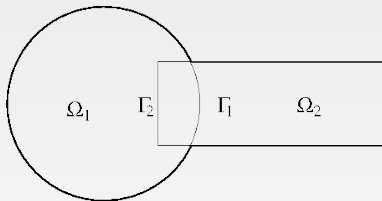
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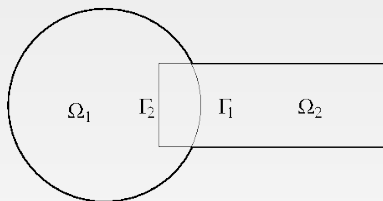
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Original Schwarz Method :

- At each t time, solutions \Rightarrow interface conditions, \Downarrow
- We must use the same time step for each subdomains. \Downarrow

Classical Schwarz Waveform Relaxation :

- Solve with different time steps, \Uparrow
- interface conditions for the time interval. \Uparrow

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with overlap

"Dirichlet" interface conditions :

$$\square_c u = \partial_t^2 u - c^2 \Delta u$$

$$\begin{array}{llll} \square_c u_1^n = 0 & \text{in } \Omega_1 \times [0, T] & \square_c u_2^n = 0 & \text{in } \Omega_2 \times [0, T] \\ u_1^n = g & \text{on } \partial\Omega \cap \overline{\Omega}_1 & u_2^n = g & \text{on } \partial\Omega \cap \overline{\Omega}_2 \\ u_1^n = u_2^{n-1} & \text{on } \Gamma_1 & u_2^n = u_1^{n-1} & \text{on } \Gamma_2 \\ u_1^n|_{t=0} = u_0 & \text{in } \Omega_1 & u_2^n|_{t=0} = u_0 & \text{in } \Omega_2 \\ \dot{u}_1^n|_{t=0} = u_1 & \text{in } \Omega_1 & \dot{u}_2^n|_{t=0} = u_1 & \text{in } \Omega_2 \end{array}$$

Finite step convergence¹ : $n > \frac{T c}{\delta}$,

δ : overlap.

¹Gander-Halpern (2004)

Bibliography

Different interface conditions :

- Neumann,
- Robin, ...

Replace " $u_j^n = u_j^{n-1}$ " by " $B_j u_j^n = B_j u_j^{n-1}$ " on Γ_j .

$$\begin{array}{ll} \square_c u_1^n = 0 & \text{in } \Omega_1 \times [0, T] \\ u_1^n = g & \text{on } \partial\Omega \cap \bar{\Omega}_1 \\ B_1 u_1^n = B_1 u_2^{n-1} & \text{on } \Gamma_1 \\ u_1^n|_{t=0} = u_0 & \text{in } \Omega_1 \\ \dot{u}_1^n|_{t=0} = u_1 & \text{in } \Omega_1 \end{array} \quad \begin{array}{ll} \square_c u_2^n = 0 & \text{in } \Omega_2 \times [0, T] \\ u_2^n = g & \text{on } \partial\Omega \cap \bar{\Omega}_2 \\ B_2 u_2^n = B_2 u_1^{n-1} & \text{on } \Gamma_2 \\ u_2^n|_{t=0} = u_0 & \text{in } \Omega_2 \\ \dot{u}_2^n|_{t=0} = u_1 & \text{in } \Omega_2 \end{array}$$

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Error variables " $u_i^n - u_i^{n-1} \rightarrow u_i^n$ " :

$$\begin{array}{ll} \square_c u_1^n = 0 & \text{in } \Omega_1 \times [0, T] \\ u_1^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_1 \\ B_1 u_1^n = B_1 u_2^{n-1} & \text{on } \Gamma_1 \\ u_1^n|_{t=0} = 0 & \text{in } \Omega_1 \\ \dot{u}_1^n|_{t=0} = 0 & \text{in } \Omega_1 \end{array} \quad \begin{array}{ll} \square_c u_2^n = 0 & \text{in } \Omega_2 \times [0, T] \\ u_2^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_2 \\ B_2 u_2^n = B_2 u_1^{n-1} & \text{on } \Gamma_2 \\ u_2^n|_{t=0} = 0 & \text{in } \Omega_2 \\ \dot{u}_2^n|_{t=0} = 0 & \text{in } \Omega_2 \end{array}$$

Can you determine " $B_i, i = 1, 2$ " as :

$$\left\{ \begin{array}{l} B_1 u_2^{n-1} \neq 0 \\ B_2 u_1^{n-1} \neq 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} B_1 u_2^n = 0 \\ B_2 u_1^n = 0 \end{array} \right. ?$$

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With the "Dirichlet to Neumann" operator DtN_1 :

$$DtN_1(v) : v \text{ on } \Gamma_1 \mapsto \frac{\partial u}{\partial \nu_1} \text{ on } \Gamma_1$$

$$\square_c u = 0 \quad \text{in } \Omega_1 \times [0, T]$$

$$u = 0 \quad \text{on } \partial\Omega \cap \bar{\Omega}_1$$

$$u = v \quad \text{on } \Gamma_1$$

$$u|_{t=0} = 0 \quad \text{in } \Omega_1$$

$$\dot{u}|_{t=0} = 0 \quad \text{in } \Omega_1$$

With $\Gamma_2 = \Gamma_1$, we get (conservative flow and $u = v$ on Γ_1) :

$$\frac{\partial u}{\partial \nu_2} = -\frac{\partial u}{\partial \nu_1} = -DtN_1(v) = -DtN_1(u)$$

$$\text{so we get : } \frac{\partial u}{\partial \nu_2} + DtN_1(u) = B_2(u) = 0 \text{ on } \Gamma_2.$$

("transparent" operator)

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With these new B_i :

$$\begin{array}{ll} \square_c u_1^n = 0 & \text{in } \Omega_1 \times [0, T] \\ u_1^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_1 \\ B_1 u_1^n = B_1 u_2^{n-1} & \text{on } \Gamma_1 \\ u_1^n|_{t=0} = 0 & \text{in } \Omega_1 \\ \dot{u}_1^n|_{t=0} = 0 & \text{in } \Omega_1 \end{array} \quad \begin{array}{ll} \square_c u_2^n = 0 & \text{in } \Omega_2 \times [0, T] \\ u_2^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_2 \\ B_2 u_2^n = B_2 u_1^{n-1} & \text{sur } \Gamma_2 \\ u_2^n|_{t=0} = 0 & \text{in } \Omega_2 \\ \dot{u}_2^n|_{t=0} = 0 & \text{in } \Omega_2 \end{array}$$

So with $u_i^n \neq 0, i = 1, 2$, we get:

$$\Rightarrow B_i u_j^n = 0, i \neq j,$$

and : $u_i^{n+1} = 0, i = 1, 2$ (we get the convergence).

Classical Schwarz Waveform Relaxation wave equation

without overlap

"transparent" operator :

$$\square_c u = \partial_t^2 u - c^2 \Delta u$$

$$\begin{array}{ll} \square_c u_1^n = 0 & \text{in } \Omega_1 \times [0, T] \\ u_1^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_1 \end{array} \quad \begin{array}{ll} \square_c u_2^n = 0 & \text{in } \Omega_2 \times [0, T] \\ u_2^n = 0 & \text{on } \partial\Omega \cap \bar{\Omega}_2 \end{array}$$

$$\begin{array}{ll} B_1 u_1^n = B_1 u_2^{n-1} & \text{on } \Gamma_1 \\ u_1^n|_{t=0} = 0 & \text{in } \Omega_1 \\ \dot{u}_1^n|_{t=0} = 0 & \text{in } \Omega_1 \end{array} \quad \begin{array}{ll} B_2 u_2^n = B_2 u_1^{n-1} & \text{on } \Gamma_2 \\ u_2^n|_{t=0} = 0 & \text{in } \Omega_2 \\ \dot{u}_2^n|_{t=0} = 0 & \text{in } \Omega_2 \end{array}$$

Optimal convergence (only 2 steps) ¹.

¹Gander-Halpern-Nataf (2003), Gander-Halpern (2004)

Wave equation

"Transparent" operator :

- 1D \Rightarrow with Engquist-Majda (order 1),
- 2-3D \Rightarrow Engquist-Majda, Higdon (order > 1),

Example 1D : step 0

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Wave equation

"Transparent" operator :

- 1D \Rightarrow with Engquist-Majda (order 1),
- 2-3D \Rightarrow Engquist-Majda, Higdon (order > 1),

Example 1D : step 1

Wave equation

"Transparent" operator :

- 1D \Rightarrow with Engquist-Majda (order 1),
- 2-3D \Rightarrow Engquist-Majda, Higdon (order > 1),

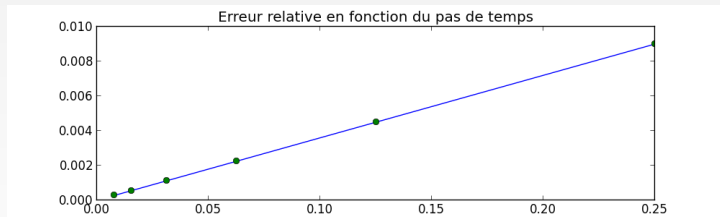
Example 1D : step 2

Wave equation

"Transparent" operator :

- 1D \Rightarrow with Engquist-Majda (order 1),
- 2-3D \Rightarrow Engquist-Majda, Higdon (order > 1),

Example 1D :



Hydro. wave model H.W. A.B.C.(1/2)

The boundary condition " $B_1 u_1 = B_1 u_2$ " :

$$\left[\prod_{j=1}^p (a_j \partial_t + c \partial_\nu)^2 \right] (a_0 \partial_t + c \partial_\nu) u_1 = \left[\prod_{j=1}^p (a_j \partial_t + c \partial_\nu)^2 \right] (a_0 \partial_t + c \partial_\nu) u_2$$

or :

$$\left[\prod_{j=1}^p (a_j \partial_t + c \partial_\nu)^2 \right] \underbrace{(a_0 \partial_t + c \partial_\nu)(u_1 - u_2)}_{a_0 \partial_t \phi_1} = 0$$

so we get :

$$(a_0 \partial_t + c \partial_\nu) u_1 = a_0 \partial_t \phi_1 + (a_0 \partial_t + c \partial_\nu) u_2,$$

$$(a_1 \partial_t + c \partial_\nu) \phi_1 = (a_1 \partial_t - c \partial_\nu) \phi_2,$$

⋮

$$(a_j \partial_t + c \partial_\nu) \phi_j = (a_j \partial_t - c \partial_\nu) \phi_{j+1},$$

⋮

$$\phi_{p+1} = 0.$$

Hydro. wave model H.W. A.B.C.(2/2)

Coupled model :

($c_f = 1000$, $J = 8$, $a = 0.4 c_f / C_{min} - 320 c_f / C_{min}$, $pc_{dte} = 0.75$)

($nsom_s = 41$, $nsom_f = 820$ by subdomain)

Absorbing Boundary
Condition, Domain
Decomposition and
Hydrodynamic Wave
Model

O. Wilk

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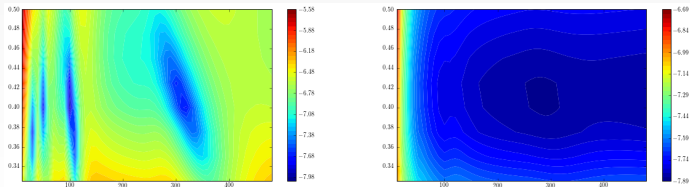
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J quadratic differences on the interface :

(left (surface), right (basin), $J(a_{min}, a_{max})$)



Conclusion

- to identify a_i minimize the convergence rate (Schwarz method),
- a small overlap (for evanescent waves),
- with flow, 3D,
- ...