

Modeling and numerics for (shallow) (water) flows

Part 2 : Beyond the Saint-Venant system

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Beginning of the story

- ▶ Saint-Venant system with sources

$$\begin{aligned}\partial_t h + \partial_x h u &= 0, \\ \partial_t h u + \partial_x (h u^2 + g h^2 / 2) &= -g h \partial_x b\end{aligned}$$

- ▶ Numerics: Finite volume method

- ▶ Positive (and entropic) scheme
 - ▶ Well-balanced scheme

- ▶ Softwares

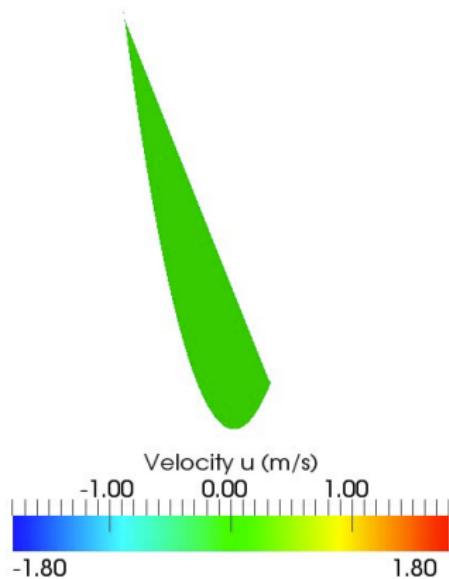
MASCARET, TELEMAC 2D (EDF-LNHE)

<http://www.opentelemac.org/index.php/presentation?id=17>

FULLSWOF (Univ. Orléans)

<http://www.univ-orleans.fr/mapmo/soft/FULLSWOF/>

A discriminant test case ?

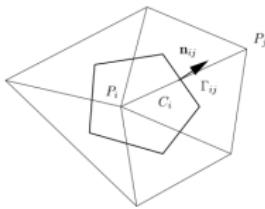


Joint work with

- ▶ ANGE group
 - J. Sainte-Marie, M.O. Bristeau,
 - Y. Penel, P. Ung, N. Seguin, E. Godlewski
- ▶ EDF LNHE – Saint-Venant Lab.
 - N. Goutal, M. Jodeau, S. Boyaval
- ▶ Academic partners
 - F. Bouchut, C. Berthon, C. Chalons, O. Delestre, S. Cordier...

Finite Volume Method

$$\partial_t u + \nabla \cdot f(u) = 0, \quad u \in \mathbb{R}^p, \quad f : \mathbb{R}^p \rightarrow \mathbb{R}^{2 \times p}$$



- ▶ Integration on the prism $C_i \times [t^n, t^{n+1}]$

$$U_i^{n+1} = U_i^n - \sum_{j \in V(i)} \sigma_{ij}^n F(U_i^n, U_j^n, n_{ij})$$

with

$$\sigma_{ij}^n = \frac{\Delta t^n |\Gamma_{ij}|}{|C_i|}, \quad F(U_i^n, U_j^n, n_{ij}) \approx \int_{\Gamma_{ij}} \int_{t^n}^{t^{n+1}} f(U(t, s)).n_{ij} dt ds$$

Relaxation solver

- ▶ Godunov scheme
 - ▶ Consistency, Stability
 - ▶ Complexity : Solution of the Riemann problem
- ▶ Relaxation models : Introduction of a larger system
 - ▶ that is hyperbolic (with LD fields)
 - ▶ that formally approaches the original ones
 - ▶ that ensures some stability property
 - ▶ for which the (homogeneous) Riemann problem is easy to solve
- ▶ Numerical algorithm
 - ▶ Definition of auxiliary variables from physical ones
 - ▶ Solution of the Riemann problem
 - ▶ Computation of the physical variables at the next time step

(Chen et al. [94], Jin-Xin [95], Bouchut [04]...)

Relaxation solver

- ▶ Example for scalar conservation law

- ▶ Original SCL

$$\partial_t u + \partial_x f(u) = 0$$

- ▶ Relaxation model

$$\begin{aligned}\partial_t u + \partial_x v &= 0 \\ \partial_t v + c^2 \partial_x u &= \frac{1}{\epsilon} (f(u) - v)\end{aligned}$$

- ▶ Stability requirement

$$c \geq |f'(u)|$$

- ▶ One retrieves the Rusanov scheme
(i.e. HLL scheme with $c_l = -c_r$)

Suliciu relaxation solver : No source

- ▶ Suliciu relaxation model for SW system

$$\begin{aligned}\partial_t h + \partial_x h \bar{u} &= 0 \\ \partial_t h \bar{u} + \partial_x (h \bar{u}^2 + \pi) &= 0 \\ \partial_t h \pi + \partial_x (h \pi \bar{u}) + c^2 \partial_x \bar{u} &= \frac{1}{\epsilon} \left(\frac{gh^2}{2} - \pi \right)\end{aligned}$$

- ▶ Stability criterion

$$c \geq h \sqrt{gh}$$

- ▶ Eigenvalues (distincts and associated to LD fields)

$$\lambda_{\pm} = u \pm \frac{c}{h}, \quad \lambda_u = u$$

(Suliciu [90,92])

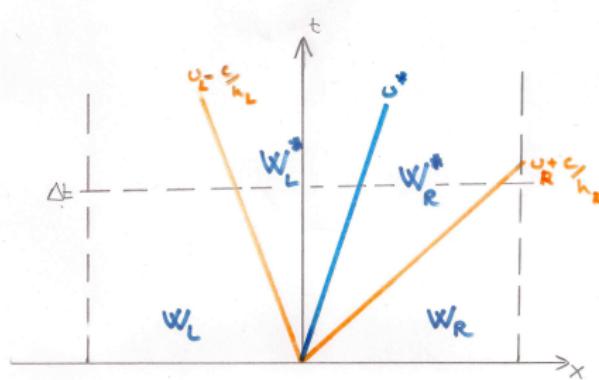
Suliciu relaxation solver : No source

- Initialization : Relaxation source term with " $\epsilon = 0$ "

$$\pi_i^n = g(h_i^n)^2/2$$

- Solution of the (homogeneous) Riemann problem

$$w_{[W_l, W_r]}^R(t, x), \quad W = (h, \bar{u}, \pi)^T$$



Suliciu relaxation solver : No source

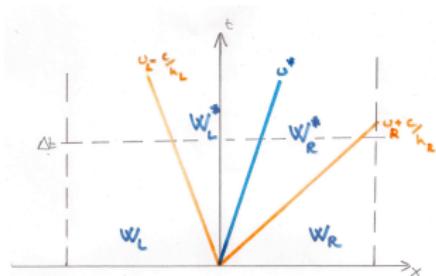
► Computation of the intermediate states

$$u^* = u_M - \frac{1}{2c} \Delta \pi, \quad \pi^* = \pi_M - \frac{c}{2} \Delta u$$

$$\tau_I^* = \tau_I + \frac{1}{2c} \Delta u - \frac{1}{2c^2} \Delta \pi, \quad \tau_r^* = \tau_r + \frac{1}{2c} \Delta u + \frac{1}{2c^2} \Delta \pi, \quad " \tau = \frac{1}{h}"$$

► Waves celerities

$$\lambda_I = u_I - \frac{c}{h_I}, \quad \lambda_u = u^*, \quad \lambda_+ = u_r + \frac{c}{h_r}, \quad " c \geq h\sqrt{gh}"$$



Extension to vacuum : Bouchut,
"Nonlinear Stability of FVM for HCL",
Birkhäuser, 2004

Suliciu relaxation scheme : With source

► First version

$$\begin{aligned}\partial_t h + \partial_x h \bar{u} &= 0 \\ \partial_t h \bar{u} + \partial_x (h \bar{u}^2 + \pi) + gh \partial_x z &= 0 \\ \partial_t h \pi + \partial_x (h \pi \bar{u}) + c^2 \partial_x \bar{u} &= \frac{1}{\epsilon} \left(\frac{gh^2}{2} - \pi \right) \\ \partial_t z &= 0\end{aligned}$$

► Eigenvalues (associated to LD fields)

$$\lambda_{\pm} = u \pm \frac{c}{h}, \quad \lambda_u = u, \quad \lambda_0 = 0$$

(Bouchut [04])

Suliciu relaxation solver : With source

- ▶ Computation of the new solution

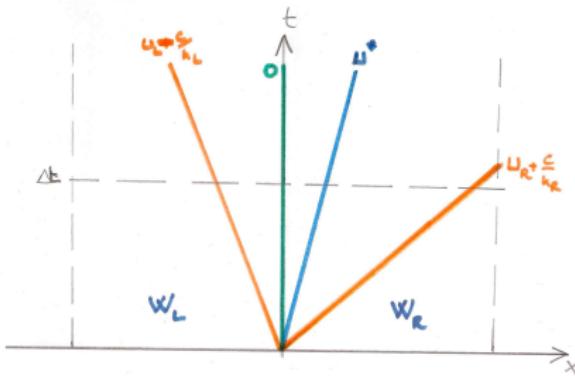
Non conservative system \rightsquigarrow Integration process (no flux)

- ▶ Properties

Consistency, WB, Positivity, Entropy inequality

- ▶ Effective computation

Eigenvalues not ordered \rightsquigarrow Multiple Riemann pbs to solve



Suliciu relaxation solver : With source

- ▶ Alternative version

$$\begin{aligned}\partial_t h + \partial_x h \bar{u} &= 0 \\ \partial_t h \bar{u} + \partial_x (h \bar{u}^2 + \pi) + gh \partial_x \tilde{z} &= 0 \\ \partial_t h \pi + \partial_x (h \pi \bar{u}) + c^2 \partial_x \bar{u} &= \frac{1}{\epsilon} \left(\frac{gh^2}{2} - \pi \right) \\ \partial_t \tilde{z} + \bar{u} \partial_x \tilde{z} &= \frac{1}{\epsilon} (z - \tilde{z})\end{aligned}$$

- ▶ Eigenvalues (associated to LD fields)

$$\lambda_{\pm} = u \pm \frac{c}{h}, \quad \lambda_u = u \text{ (double)}$$

Riemann problem is under-determined...

Suliciu relaxation solver : With source

- Linearized alternative version

$$\begin{aligned}\partial_t h + \partial_x h \bar{u} &= 0 \\ \partial_t h \bar{u} + \partial_x (h \bar{u}^2 + \pi) + g \bar{h} \partial_x \tilde{z} &= 0 \\ \partial_t h \pi + \partial_x (h \pi \bar{u}) + c^2 \partial_x \bar{u} &= \frac{1}{\epsilon} \left(\frac{gh^2}{2} - \pi \right) \\ \partial_t \tilde{z} + \bar{u} \partial_x \tilde{z} &= \frac{1}{\epsilon} (z - \tilde{z})\end{aligned}$$

- Eigenvalues (associated to LD fields)

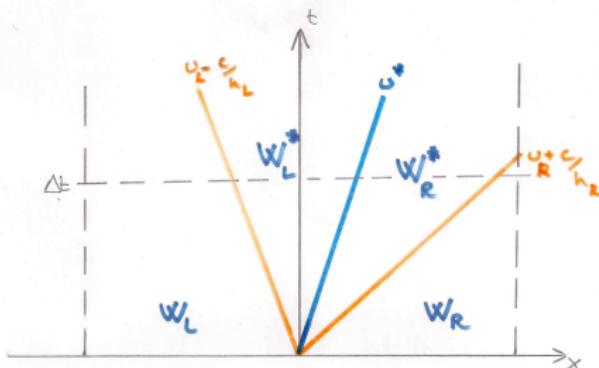
$$\lambda_{\pm} = u \pm \frac{c}{h}, \quad \lambda_u = u \text{ (double)}$$

Suliciu relaxation solver : With source

► Solution of the Riemann problem

Same structure as in the conservative case...

But different intermediate states

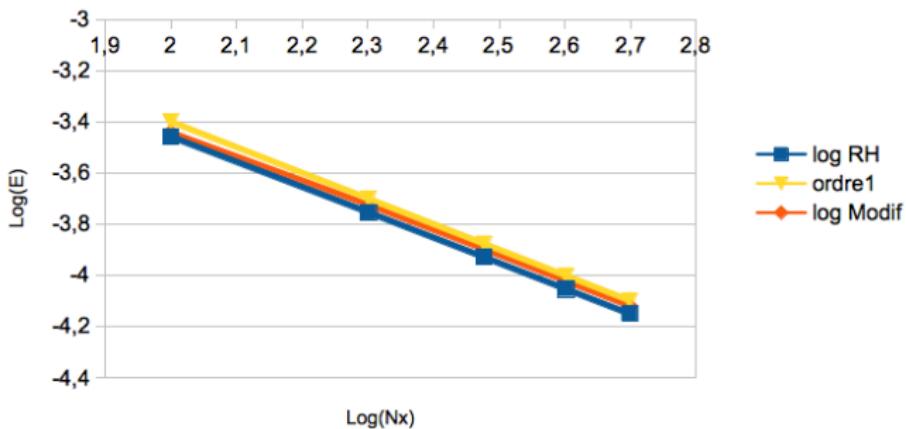


► Properties : Consistency, WB, Positivity, Entropy inequality

$$\bar{h} = h_M$$

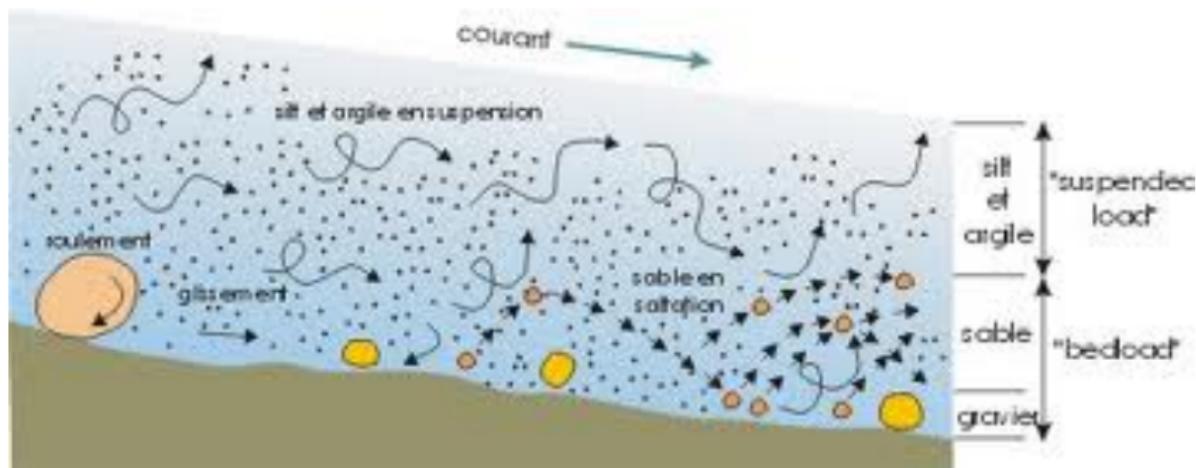
(Introduced as a wb simple Riemann solver : Galice [02])

Suliciu relaxation solver : Numerical test



Comparison between
Suliciu without source + Hydrostatic reconstruction
and
Suliciu with source

Suliciu relaxation solver : Towards morphodynamics



Morphodynamics process
Suspended- and bedload

Suliciu relaxation solver : Towards morphodynamics

► Saint-Venant – Exner model

$$\partial_t h + \partial_x q_w = 0,$$

$$\partial_t q_w + \partial_x \left(\frac{q_w^2}{h} + \frac{g}{2} h^2 \right) = -gh\partial_x b - \frac{\tau_b}{\rho_w},$$

$$\rho_s(1-p)\partial_t b + \partial_x q_s = 0,$$

► Properties

- Hyperbolic for classical choices of $q_s(h, \bar{u}, \partial_x b)$
- Eigenvalues hard to compute except for special choices of q_s
- No dynamics in the solid phase
- No transport in the fluid phase

(Hudson [05], Castro [08], Benkhaldoun [09], Cordier [11]...)

Suliciu relaxation solver : Towards morphodynamics

- ▶ Sediment flux formula (Grass [81])

$$q_s = A_g |\bar{u}|^2 \bar{u}$$

- ▶ Shields parameter

$$\theta = \frac{|\tau_b|/\rho_w}{g(s-1)d_m}, \quad s = \rho_s/\rho_w$$

- ▶ Threshold sediment flux formulae

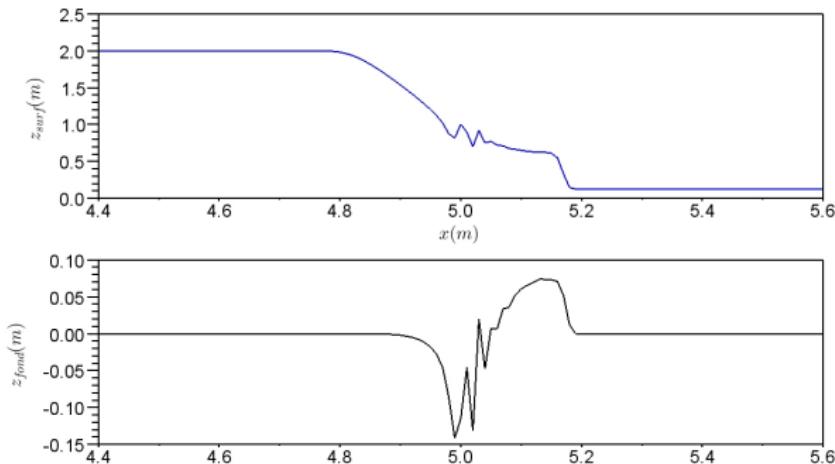
$$q_s = \Phi \sqrt{g(s-1)d_m^3}$$

- ▶ Meyer-Peter & Müller [48] : $\Phi = 8(\theta - \theta_c)_+^{3/2}$
- ▶ Engelund & Fredsoe [76]: $\Phi = 18.74(\theta - \theta_c)_+ (\theta^{1/2} - 0.7\theta_c^{1/2})$
- ▶ Nielsen [92] : $\Phi = 12\theta^{1/2}(\theta - \theta_c)_+ \dots$

Numerical strategies for bedload transport

- ▶ Steady state strategy
 - ▶ Hydrodynamic computation on fixed topography
~~ Steady state
 - ▶ Evolution of topography forced by hydrodynamic steady state
 - ▶ Efficient for phenomena involving very different time scales
- ▶ External coupling (time splitting)
 - ▶ Use of two different softwares for hydro- and morphodynamics
 - ▶ Allow to use existing solvers and different numerical strategies
 - ▶ Actual strategy at EDF (MASCARET-COURLIS)
 - ▶ Efficient for low coupling
- ▶ Internal coupling
 - ▶ Solution of the whole system at once
 - ▶ Need for a new solver
 - ▶ Efficient for general coupling

Dam break : Failure for external coupling



External coupling (M. Jodeau)

Suliciu relaxation solver : Towards morphodynamics

► Relaxation model

$$\partial_t h + \partial_x h \bar{u} = 0$$

$$\partial_t(h\bar{u}) + \partial_x(h\bar{u}^2 + \pi) + gh\partial_x b = 0$$

$$\partial_t \pi + \bar{u}\partial_x \pi + \frac{\alpha^2}{h}\partial_x u = \frac{1}{\epsilon} \left(\frac{gh^2}{2} - \pi \right)$$

$$\partial_t b + \partial_x \omega = 0$$

$$\partial_t \omega + \left(\frac{\beta^2}{h^2} - \bar{u}^2 \right) \partial_x b + 2\bar{u}\partial_x \omega = \frac{1}{\epsilon}(q_s - \omega)$$

► Definitions

- (π, ω) : Auxiliary variables (fluid pressure, sediment flux)
- $\epsilon > 0$: (Small) relaxation parameter
- $(\alpha, \beta) > 0$: Have to be fixed to ensure stability

Suliciu relaxation solver : Towards morphodynamics

► General properties

- Formally tends to SW-Exner model when ϵ tends to 0
- Always hyperbolic ($h \neq 0$) and LD fields

► Stability requirement

$$a^2 \geq h^2 p'(h) = gh^3, \quad b^2 \geq (hu)^2 + gh^2 \partial_u Q_s$$

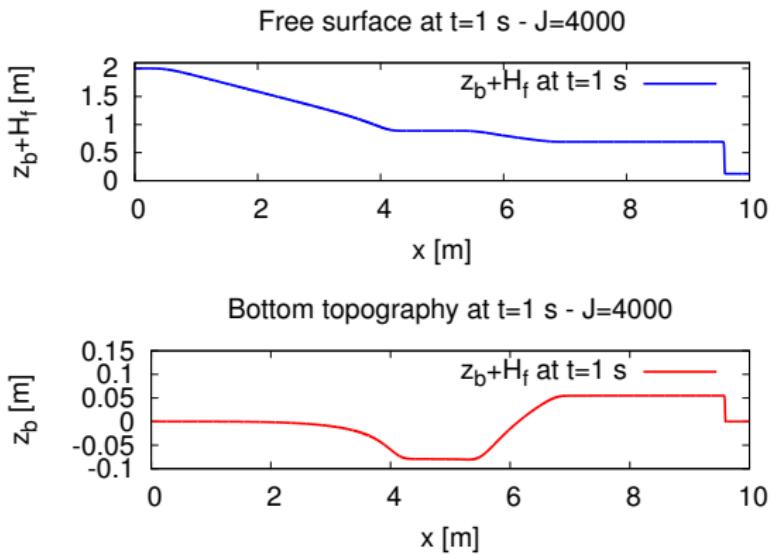
► Specificities for morphodynamics

- No explicit dependency on sediment flux q_s
- Ordered eigenvalues

$$u - \frac{b}{H} < u - \frac{a}{H} < u < u + \frac{a}{H} < u + \frac{b}{H}$$

- Riemann problem easy to solve for $a < b \dots$
But case $b < a$ leads to unaffordable computations...
With linearized version : Riemann pb may have no solution !

Dam break : Internal coupling



Internal coupling (O. Delestre)

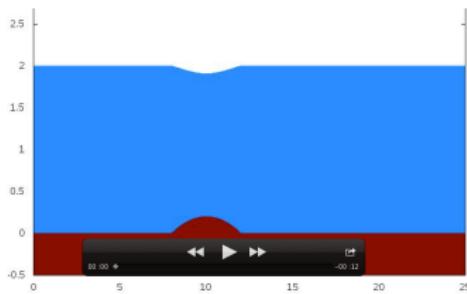
"Steady" flow over a movable bump



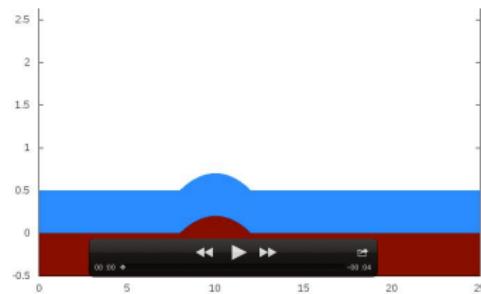
Dunes



Antidunes

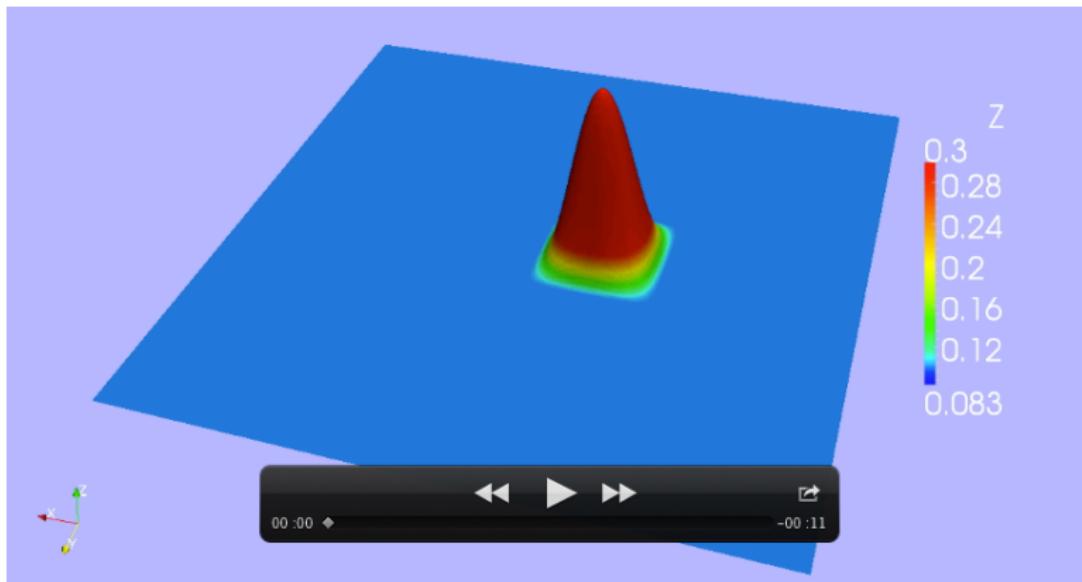


Fluvial flow



Torrential flow

"Steady" flow over a movable bump in 2d



Fluid models for geophysic flows

- ▶ Incompressible Navier Stokes equations
 - ▶ Efficient model for a large class of flows
 - ▶ CPU time (3d computations)
 - ▶ Complex implementation
(moving boundaries, not connected domains...)
 - ▶ Robustness of the softwares for stiff flows
(dam break, hydraulic jumps...)
- ▶ Shallow water equations
 - ▶ Easy implementation (fixed domain)
 - ▶ CPU time (2d computations)
 - ▶ Robustness of the software
 - ▶ Agreement with experiments... but not for all flows !
 - ▶ Constant velocity along the z-direction
 - ▶ Hydrostatic approximation

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From hydrostatic NS equations to multilayer models

- ▶ General Idea
 - ▶ To derive a 2d (of hyperbolic type) model that takes into account vertical effects in the flow
- ▶ Derivation
 - ▶ Vertical discretization of the fluid into M layers
 - ▶ Vertical integration of hydrostatic incomp. NS equ. by layer
- ▶ Consequences
 - ▶ Each layer has its own velocity
 - ▶ Coupling between the layers through
 - ▶ Pressure term (global coupling)
 - ▶ Mass exchange ("local" coupling : interface condition for mass equation)
 - ▶ Viscous effect (local coupling : interface condition for momentum equation)

Multilayer model : Simplified case

- ▶ Hydrostatic incompressible Euler equ. with free surface

$$\begin{aligned}\partial_x u + \partial_z w &= 0, \\ \partial_t u + \partial_x u^2 + \partial_z uw + \partial_x p &= 0, \\ \partial_z p &= -g,\end{aligned}$$

with

$$t > 0, \quad x \in \mathbb{R}, \quad z_b(x) \leq z \leq \eta(t, x),$$

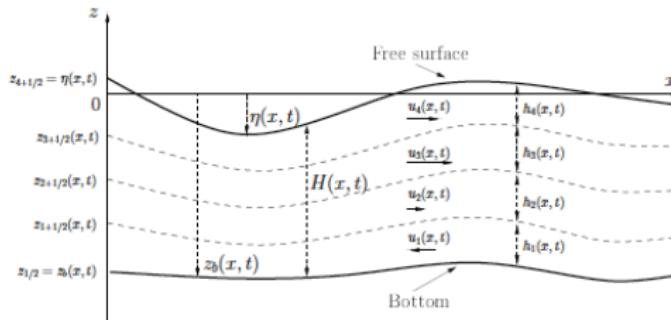
- ▶ Boundary conditions

$$\partial_t \eta + u_\eta \partial_x \eta - w_\eta = 0$$

Multilayer model : Vertical discretization

► Velocity

$$u(t, x, z) = \sum_{\alpha=1}^M 1_{[z_{\alpha-1/2}, z_{\alpha+1/2}]} \bar{u}_\alpha(t, x)$$



Multilayer model : Vertical integration

- ▶ Equations after integration on a layer

$$\partial_t h_\alpha + \partial_x h_\alpha \bar{u}_\alpha = G_{\alpha+1/2} - G_{\alpha-1/2},$$

$$\partial_t h_\alpha \bar{u}_\alpha + \partial_x h_\alpha \bar{u}_\alpha^2 + gh_\alpha \partial_x H$$

$$= -gh_\alpha \partial_x b + u_{\alpha+1/2} G_{\alpha+1/2} - u_{\alpha-1/2} G_{\alpha-1/2}$$

- ▶ Mass exchange term

$$G_{\alpha+1/2} = \partial_t z_{\alpha+1/2} + u_{\alpha+1/2} \partial_x z_{\alpha+1/2} - w_{\alpha+1/2}$$

- ▶ Natural conditions for lowest and uppest layers

$$G_{1/2} = G_{N+1/2} = 0$$

- ▶ What choice for the others ?

Multilayer model : Variable density

- ▶ Equations after integration on a layer

$$\begin{aligned}\partial_t \rho_\alpha h_\alpha + \partial_x \rho_\alpha h_\alpha \bar{u}_\alpha &= G_{\alpha+1/2} - G_{\alpha-1/2}, \\ \partial_t \rho_\alpha h_\alpha \bar{u}_\alpha + \partial_x \rho_\alpha h_\alpha \bar{u}_\alpha^2 + \partial_x h_\alpha p_\alpha \\ &= p_{\alpha+1/2} \partial_x z_{\alpha+1/2} - p_{\alpha-1/2} \partial_x z_{\alpha-1/2} \\ &\quad + u_{\alpha+1/2} G_{\alpha+1/2} - u_{\alpha-1/2} G_{\alpha-1/2}\end{aligned}$$

- ▶ Mass exchange term

$$G_{\alpha+1/2} = \rho_{\alpha+1/2} (\partial_t z_{\alpha+1/2} + u_{\alpha+1/2} \partial_x z_{\alpha+1/2} - w_{\alpha+1/2})$$

- ▶ Pressure terms

$$p_\alpha = \frac{1}{h_\alpha} \int_{z_{\alpha-1/2}}^{z_{\alpha+1/2}} p(x, z, t) dz, \quad p_{\alpha+1/2} = p(x, z_{\alpha+1/2}, t),$$

Multilayer model : Different models

- ▶ No exchange : Multifluid problems

$$G_{\alpha+1/2} = 0$$

↔ M superposed Saint-Venant systems (Castro et al. [01]...)

- ▶ Horizontal layers

$$\partial_t z_{\alpha+1/2} = \partial_x z_{\alpha+1/2} = 0 \quad \Rightarrow \quad G_{\alpha+1/2} = -w_{\alpha+1/2}$$

↔ 1 equ. for h_M and M velocity equations (Rambaud [12])

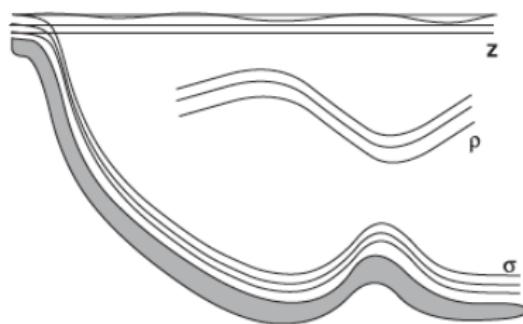
- ▶ Adaptative layers

$$h_\alpha(t, x) = \lambda_\alpha H(t, x)$$

↔ 1 equ. for H and M velocity equations (ABPSa [11])

Multilayer model : Links with classical NS discretization

- ▶ Isopycnal coordinates
 - ~~ Stratifications are imposed in the model
- ▶ $z-$ coordinates
 - ~~ Pbs to deal with complex bottom and water surface
- ▶ $\sigma-$ coordinates
 - ~~ Well-adapted to geometry but may diffuse stratifications



Multilayer model : System of equations

$$\partial_t \sum_{\alpha=1}^N \rho_\alpha l_\alpha H + \partial_x \sum_{\alpha=1}^N \rho_\alpha l_\alpha H u_\alpha = 0$$

$$\begin{aligned} \partial_t (\rho_\alpha h_\alpha u_\alpha) + \partial_x (\rho_\alpha h_\alpha u_\alpha^2 + h_\alpha p_\alpha) \\ = u_{\alpha+1/2} G_{\alpha+1/2} - u_{\alpha-1/2} G_{\alpha-1/2} \\ + p_{\alpha+1/2} \partial_x z_{\alpha+1/2} - p_{\alpha-1/2} \partial_x z_{\alpha-1/2} \end{aligned}$$

$$\begin{aligned} \partial_t (\rho_\alpha h_\alpha T_\alpha) + \partial_x (\rho_\alpha h_\alpha T_\alpha u_\alpha) \\ = T_{\alpha+1/2} G_{\alpha+1/2} - T_{\alpha-1/2} G_{\alpha-1/2} \end{aligned}$$

$$\rho_\alpha = \rho(T_\alpha)$$

$$p_\alpha = \frac{1}{h_\alpha} \int_{z_{\alpha-1/2}}^{z_{\alpha+1/2}} p(x, z, t) dz, \quad p_{\alpha+1/2} = p(x, z_{\alpha+1/2}, t)$$

$$G_{\alpha+1/2} = \sum_{j=1}^{\alpha} \frac{\partial \rho_j h_j}{\partial t} + \sum_{j=1}^{\alpha} \frac{\partial \rho_j h_j u_j}{\partial x}$$

Multilayer model : Properties

- ▶ Invariant domain
Positivity of total water depth
- ▶ Global energy inequality

$$E_{sv,\alpha}^N = \frac{\rho_\alpha h_\alpha u_\alpha^2}{2} + \frac{g \rho_\alpha (z_{\alpha+1/2}^2 - z_{\alpha-1/2}^2)}{2}$$

$$\frac{\partial}{\partial t} \left(\sum_{\alpha=1}^N E_{sv,\alpha}^N \right) + \frac{\partial}{\partial x} \left(\sum_{\alpha=1}^N u_\alpha \left(E_{sv,\alpha}^N + \frac{g}{2} \rho_\alpha h_\alpha H \right) \right) = 0$$

- ▶ Hyperbolicity
 - ▶ Bi-layer model is hyperbolic
 - ▶ Possible local loss of hyperbolicity for more than three layers

Numerics : Kinetic interpretation of SW system

- ▶ Saint-Venant system

$$\begin{aligned}\partial_t h + \partial_x h u &= 0, \\ \partial_t h u + \partial_x (h u^2 + gh^2/2) &= -gh \partial_x b\end{aligned}$$

- ▶ Density function

$$M(t, x, \xi) = \frac{h(t, x)}{c(t, x)} \chi \left(\frac{\xi - u(t, x)}{c(t, x)} \right), \quad c = \sqrt{\frac{gh}{2}}$$

with χ an even probability function, ξ a kinetic velocity

- ▶ Kinetic equation

$$\partial_t M + \xi \partial_x M - g \partial_x z \partial_\xi M = Q(x, t, \xi)$$

~ Equivalency with SW system : Integration in ξ vs. $(1, \xi)^T$

Numerics : Kinetic scheme (derivation, no source)

► Kinetic level

- Definition of M_i^n from (h_i^n, u_i^n)
- Upwind scheme for the linear transport kinetic equation

$$f_i^{n+1} = M_i^n - \frac{\Delta t}{\Delta x} \left(f_{i+1/2}^n - f_{i-1/2}^n \right), \quad f_{i+1/2}^n = \begin{cases} \xi M_i^n & \text{if } \xi > 0 \\ \xi M_{i+1}^n & \text{if } \xi < 0 \end{cases}$$

► Macroscopic scheme

Integration in ξ

$$(F^h)_{i+1/2}^n = \int f_{i+1/2}^n d\xi, \quad (F^q)_{i+1/2}^n = \int \xi f_{i+1/2}^n d\xi$$

► Source term

Perthame-Simeoni [Calcolo, 01] : Numerical integration processes

Numerics : Kinetic scheme (properties, no source)

► Simplicity

Macroscopic fluxes can be computed analytically if probability function χ is simple enough

$$\chi(\omega) = \frac{1}{2\sqrt{3}} \mathbb{I}_{[-\sqrt{3}, \sqrt{3}]}, \quad \chi(\omega) = \left(1 - \frac{\omega^2}{4}\right)_+^{1/2}$$

No need for the computation of the eigenvalues

► Stability

- Positivity for water depth
- Entropy inequality
- CFL condition

$$\Delta t^n \leq \min_i \left(\frac{\Delta x_i}{|u_i^n| + \frac{\omega_m}{\sqrt{2}} \sqrt{gh_i^n}} \right)$$

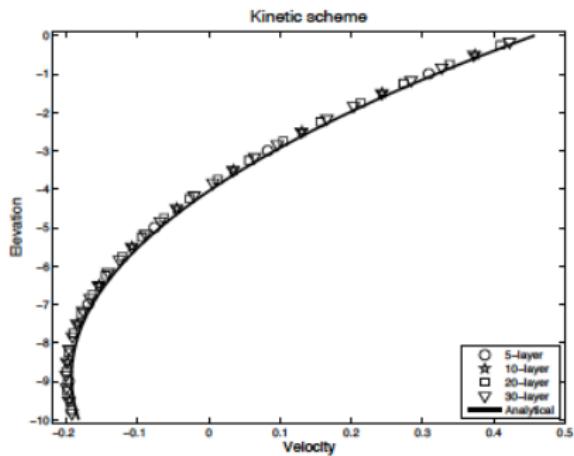
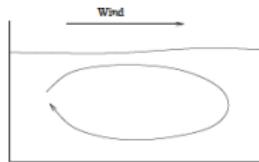
Numerics : Multilayer system

- ▶ Extension of the kinetic interpretation
 - ~~ Construction of a kinetic scheme
- ▶ Modified CFL condition
 - ~~ Takes into account mass exchange terms
 - ~~ Positivity of water depth and tracer concentration
- ▶ Extension of the hydrostatic reconstruction
 - ~~ Preservation of relevant equilibria
- ▶ Variable density case
 - ▶ Computation of solution : Non linear problem to solve
 - ▶ Boussinesq assumption : Back to simple case

Numerics : 3d dam break



Numerics : Wind-induced circulation

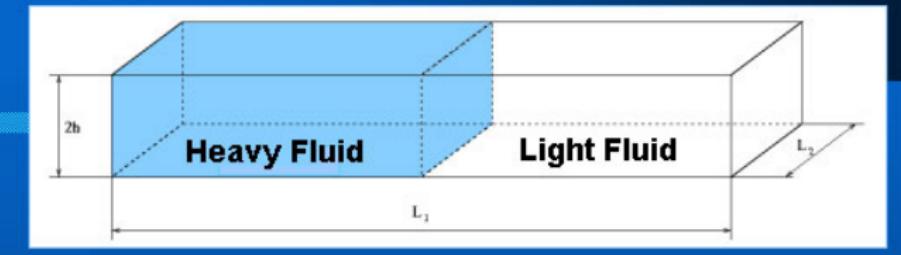


Numerics : Stratified fluid ?



Numerics : Lock exchange

Lock-Exchange – 2D Simulation



Numerics : Gibraltar straight



Numerics : Ocean in bottles



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